

Table of Contents

	Navigation / Document Conventions	v
	Table of Contents	vii
	List of Figures	xvii
	List of Tables	xviii
1	Introduction.....	1
	Features	1
	Software Version Requirements.....	3
	Where to Start?.....	3
2	Installation.....	5
	Anti-static procedures	5
	Loading firmware.....	5
	Mounting.....	5
	Location in Airframe	6
	Orientation	6
	Sizes & Weights	6
	Vibration Isolation.....	7
	Connectors	8
	Connectors, Pins, and Crimping Tools	12
	Power	17
	Measuring Main Voltage.....	17
	Minimum/Maximum Voltages	18
	Current Draw.....	18
	Ground loops.....	18
	RC Receiver	19
	MP1028 ^{g2} /MP2028 ^{g2} /MP2128g2 / MP2128HELI2.....	20
	RC Signals from the Receiver	20
	RC Autopilot By-pass Devices.....	21
	Servo Board.....	21

	Servo Board Power Input	22
	Servo Voltage Sense.....	22
	Measuring Servo Voltage	22
	Servo Board Power Capabilities.....	23
	GPS.....	23
	Transition Cable Location.....	24
	GPS Backup Battery	25
	Mounting the GPS antenna	26
	External GPS receiver.....	27
	AGL	29
	MP - AGL	29
	Current Draw.....	30
	Mounting the AGL	31
	Noise.....	32
	AGL Scaling	34
	Compass	35
	Serial COM Port.....	35
	Pitot tube	36
	Static Air Inlet.....	37
	Altitude Sensor	37
	Speed controller.....	37
	Radio Modems.....	37
	Wiring Diagrams	38
3	Communicating with your MicroPilot Autopilot.....	43
	Serial port	43
	Software.....	43
	Using HyperTerminal & Similar	44
	Default Settings.....	44
	Connect to PC.....	44
	Using HORIZON ^{mp}	47
	Installing HORIZON ^{mp}	47
	Configuring HORIZON ^{mp}	48
	Working with .vrs files.....	49
4	Servo configurations	55

About Servo Configurations	55
Making Servo Adjustments	62
Servo Travel Modes	64
Servo Travel Config Fields	65
Coarse Servo Mixing	66
Custom Servo Mixes	67
CH5 Setup – CIC/PIC	68
Failsafe Setup	69
5 Post Installation Checks.....	71
Follow these Steps.....	71
Vibration Analyser.....	76
Fly Away Prevention Measures.....	80
HORIZON ^{mp} Preparation for First Flight	82
The Next Step.....	82
Test Fly in PIC	83
6 Operating your MicroPilot Autopilot.....	85
Power on	85
Faking GPS Lock	86
Preflight Checks.....	87
Cold/Warm Soak.....	87
Takeoff.....	89
Manual takeoff.....	89
Current Altitude = 0 Conditions.....	89
Landing.....	89
Approach Speed, Final Reduce Speed, and Minimum Target Speed	89
GCS CIC Modes	90
How to choose modes.....	90
RPV Mode.....	90
Failures in RPV Mode	90
Fly by Camera.....	91
Orbit by Camera.....	92
Priority of Control Modes	92
Fatal Errors	92
Multiple Fatal Errors	93

	Indication.....	93
	AutoPilot Action.....	94
	User-Defined Fatal Errors	108
	GPS Error Messages	109
	Warnings	110
	Multiple Warnings.....	111
	Indication.....	111
	User-Defined Warnings.....	119
	Clearing a User-defined Warning Code	120
	Temperature Effects	122
	Data log	122
7	Setting Parameters	125
	Main Initial Settings.....	125
	Flight tab	125
	Servos tab.....	130
	Sensors tab.....	132
	GPS tab	134
	Other tab	136
	Heli tab: Kalman Filter Parameters.....	138
	GPS antenna position	139
	On-ground detection.....	140
	Help with Setting up Fields / Features.....	140
8	PID Feedback Loops.....	141
	PID Loops	141
	About PIDs.....	143
	PTerm	143
	ITerm	143
	DTerm.....	144
	Feed Forward	146
	PID Loops with Feed Forward	147
	New Feed Forward Terms in 3.6	147
	Input Max/Min & Result Anti-windup Max/Min	148
	Setting Gains	148
	Feedback Loop Configuration	149

	Example: Level Flight	149
	Example: Pre-Takeoff.....	150
	Example: Climb	150
	Example: Descent.....	151
9	Stability Derivatives & the HORIZON^{mp} Simulator	153
	AVL Text Editor.....	153
	Opening a Project	153
	Generating stability derivatives.....	154
	Export Derivatives to DFN Editor.....	157
10	MicroPilot Autopilot Setup	159
	Tuning Feedback Loops.....	159
	The gain setting process for fixed wing aircraft	160
	Recording PID Values	160
	To Start	162
	The Inner Loops.....	163
	Rapid Rolling side to side (several times each second).....	164
	Fast Pitch Oscillations (1 Hz or more)	164
	Rapid Yaw Oscillations (1 Hz or more).....	164
	Navigation Loops	164
	Navigation is sloppy	165
	S-Turning or Slow rolling oscillations.....	165
	Turns sharper in one direction than the other	166
	Altitude and Airspeed Control.....	167
	Lots of overshoot on a climb.....	167
	Lots of overshoot on a descent	167
	Flies consistently lower/higher than the desired altitude	168
	Always flies slower or faster than the desired airspeed	168
	Doesn't hold airspeed well.....	168
	Descends too slowly or climbs instead of descending	168
	Flies too fast/slow when climbing	169
	Descending when the UAV should be climbing	169
	Slow Pitch Oscillation (several seconds)	169
	Slow Altitude Oscillations (several seconds)	169
	Slow Airspeed Oscillations (several seconds)	170

	Slow Airspeed Oscillations combined with Slow Altitude Oscillations (ten or tens of seconds).....	170
	After Each Tuning Flight.....	171
	Using Gain Schedules	172
	Autonomous Takeoff Tips	175
	UAV Pitches Up or Down immediately from Catapult	175
	UAV pitches down as soon as climb speed is reached.....	176
	Adjusting Gains for Autonomous Landing	177
	Attempting Multiple Circuit Approaches.....	177
	In-flight Gain adjustment.....	178
	Gains panel.....	179
	MP Status Monitor	180
	Graphs	181
	Other buttons	183
11	Commands	185
	Data Types	186
	Unit Conversions.....	187
	Comments in Fly Files	187
	Reaching waypoints.....	188
	Relative Waypoints and Origin	189
	Basic Flight Commands	189
	Two Stage Glideslope	209
	Advanced Flight Commands	216
	Calculation Commands.....	226
	Thread and Pattern Commands.....	230
	Skip commands	242
	Wait Commands	244
	Skip & WaitCommands for Heading Fields.....	247
	In-flight Failure Patterns.....	249
	Recoverable/Unrecoverable	250
	Failure Timeouts	251
	Control failure.....	251
	Fatal error	251
	Loss of GPS signal.....	252
	Loss of engine power	254

	Low battery voltage	255
	RC link failure.....	256
	HORIZON ^{mp} communication link failure	256
	Special Field Definitions for Fly Files.....	257
	Compiler	260
	Run Time Errors.....	260
12	MicroPilot Autopilot Fields.....	261
	Sign Conventions.....	262
	Autopilot Units.....	263
	Setup Fields.....	265
	Launch	265
	Flight	271
	Recovery.....	276
	Servos & Mixing	279
	Sensors.....	286
	GPS	291
	<i>HORIZON^{mp} GCS & Terminal communication</i>	294
	Failures	299
	Limits	302
	Batteries.....	306
	Integrators.....	307
	Camera Targeting	307
	LRC.....	311
	<i>MP2028^{XP} (Target)</i>	311
	Video Overlay.....	312
	VRS Locking	312
	Runway Fields.....	313
	Data log Configuration Fields	314
	PID Feedback Loops.....	322
	Watchdog Fields	330
	Stall / Tumble Recovery Fields.....	330
	PID Loops for Stall & Tumble Recovery	333
	Glide Landing Function	338
	Simulator Calibration Override	339

	Servos.....	340
	Other.....	340
	State Fields.....	341
	Attitude.....	341
	Other sensors.....	344
	Kalman Filter Estimates	347
	High Precision Attitude	349
	<i>GPS & Navigation</i>	349
	HORIZON ^{mp} GCS and Terminal Communication.....	357
	Status.....	361
	Table Lookup Functions	369
	Servo & Flight Control Fields.....	370
	Command State	374
	Raw Sensors.....	380
	Feedback Loop State	383
	Origin Fields.....	387
	Transponder Setup Fields	388
	Other State Fields	389
	Bind Feature State Fields.....	392
	Watchdog State Fields	393
	Helicopter Specific Fields	394
13	Setup Program	399
	Setting Hexadecimal values.....	401
14	Data log & Telemetry	402
	About the Data log	402
	Starting/Stopping.....	402
	Resetting/clearing	403
	Protecting Data log.....	403
	Buffering.....	403
	Data log Capacity & Recording Rate.....	404
	Log Recording Time.....	404
	Circular data log recording	405
	Backward filter.....	405
	List of Data log fields	405

	Status fields decoded	410
	GPS Time	412
	Custom Data log Features	413
	User-defined Data log Fields	413
	Using Unused Data log Servo Fields to Record Other Values.....	414
	Telemetry.....	414
	User Defined	414
	GPS time.....	415
	Standard Telemetry.....	415
	MP-3X Status.....	419
	Camera Telemetry	420
15	Loading New Code.....	423
	MP2028g Small flash chip firmware	423
	Updating software	423
	Last Firmware Versions available.....	423
	Correct Firmware type for Autopilot.....	424
	Installation.....	426
16	Problem Solving.....	429
	Initialization	429
	GPS	429
	Servos.....	432
	Takeoff.....	432
	Flight.....	434
	Circuit and Landing.....	434
	Radio Reception	435
	Other Problems.....	436
	After a Crash or Hard Landing.....	438
	Further Information	438
17	RMA's and SUPPORT	439
	Warranty	439
	RMA's	440
	RMA Standards.....	441
	Charges	442
	RMA Services	444

Support	446
Support By TeamViewer	448
Support By Skype	449
Support Site Content.....	449
Finding Your Autopilot's Serial Number	449
List of Serial Number Prefixes	450
Primary COM port	463
UARTs	463
CMOS vs RS232 Levels.....	464
About the Watchdog Feature	469
Watchdog Failure Signal.....	469
Watchdog Trigger Conditions.....	470
Testing	470
Watchdog Fields	470
Autopilot.....	471
HORIZON ^{mp} and other GUI	471
XTENDER.....	471

Appendices

A.	TPU Channels and CAN Lines	455
	MP1028g/MP2028g&MP1028g2/MP2028g2/MP2128g2/MP2128HELI2	455
	MP1028g2/MP2028g2/MP2128g2/MP2128HELI2 Only	456
B.	Serial Ports & UARTs.....	463
	Available Ports.....	463
	RS485.....	464
C.	MP1028^g Appendix	465
D.	Watchdog Feature.....	469
E.	Open source code.....	471
Index	474