

---

# Table of Contents

	Navigation / Document Conventions .....	v
<b>1</b>	<b>Introduction .....</b>	<b>1</b>
	Redundancy Board .....	1
	Triple Redundancy .....	1
	Software Requirements .....	2
	Features .....	2
	Package Contents .....	3
<b>2</b>	<b>Installation .....</b>	<b>5</b>
	Weights and Overall Dimensions .....	6
	Power .....	6
	Min/max input voltages .....	7
	Servo Power .....	8
	Connectors .....	8
	Terminating Leads Of J3/J4 Wiring Harnesses .....	9
	MP2128 <sup>3X</sup> StatusLights .....	9
	MP2128 <sup>3X</sup> Redundancy Feature .....	10
<b>3</b>	<b>Loading Firmware .....</b>	<b>13</b>
	Correct Firmware type for Autopilot .....	13
	Physical connections .....	13
	Firmware update procedure .....	13
<b>4</b>	<b>Terminology .....</b>	<b>16</b>
<b>5</b>	<b>Failure Detection and Board Switching .....</b>	<b>19</b>
	Connected Board .....	19
	Sensor Failure .....	19
<b>6</b>	<b>Synchronisation .....</b>	<b>23</b>
	Sensor Values .....	23
	Communication Link .....	23
	Fly Files .....	24
	Other Synchronisation Details .....	25
	VRS Files .....	25
<b>7</b>	<b>Communication Ports .....</b>	<b>27</b>
	Serial Com Ports .....	27
	Serial Protocols .....	28
	RADA .....	28
	RADB .....	28
	APCOM_1b/2b/3b .....	28
	COM1/2/3_RS .....	29
	MPCOM4_1b/2b/3b .....	29

Triple Redundant ***Autopilot***  
**Installation & Operation**

<b>8</b>	<b>Servos .....</b>	<b>31</b>
<b>9</b>	<b>High Current Drivers (Relays) .....</b>	<b>33</b>
	Controlling Relay Channels .....	33
	Relay Specifications .....	34
	Relay Status .....	35
<b>10</b>	<b>ADC Inputs .....</b>	<b>37</b>
<b>11</b>	<b>CAN Bus .....</b>	<b>39</b>
<b>12</b>	<b>GPIO .....</b>	<b>41</b>
	The MP2128 <sup>3x</sup> GPIO Channels .....	41
	TPU & GPIO Channels .....	42
<b>13</b>	<b>VRS File Configuration .....</b>	<b>45</b>
	MP3X- Specific Fields .....	45
	Mounting Orientation Configuration .....	45
	Differences Between VRS Files .....	46
<b>14</b>	<b>Manual Flight (LRC-PIC) .....</b>	<b>49</b>
	LRC-PIC .....	49
	PPM Encoder .....	49
	LRC Base Configuration .....	50
<b>15</b>	<b>HORIZON<sup>mp</sup> Setup .....</b>	<b>51</b>
<b>16</b>	<b>qHWIL .....</b>	<b>53</b>
<b>17</b>	<b>HORIZON<sup>mp</sup> Instruments .....</b>	<b>55</b>
	Status Lights .....	55
	HORIZON <sup>MP</sup> Instruments .....	57
<b>18</b>	<b>How to Fail and disable sensor checks on boards .....</b>	<b>59</b>
	Disabling/Enabling a Board .....	59
	Disable sensor checks on a board .....	59
<b>19</b>	<b>VRS Editing/Transmission .....</b>	<b>61</b>
	Upload VRS .....	61
	Downloading a VRS .....	63
	Editing a VRS .....	64
<b>20</b>	<b>Plug-ins – Special Behaviour .....</b>	<b>65</b>
	Sensor Monitor Plug-in .....	65
	Reading Fields .....	65
	Writing Fields .....	66
	Error Monitor Plug-in .....	66
<b>21</b>	<b>Compass Calibration .....</b>	<b>69</b>

---

22	Using Differential GPS with the NovAtel GPS Receiver .....	71
23	Troubleshooting .....	73
	Power up .....	73
	Power up .....	75
	(continued) .....	75
	Vibration .....	75
	Error on RC CH5 Input .....	76
	LRC-PIC mode .....	76
	GPS.....	76
	HyperTerminal .....	78
	HORIZON <sup>mp</sup> .....	78
	Loss of communication after transmitting VRS or flashing autopilot.....	79
24	Appendix.....	80
	MP3X-Specific Fields .....	80
	Status Field Bit Details .....	85
	Redundancy Status Bits .....	86
	MP3X Status [Left/Right] .....	86
	MP3X Comm Status [Left/Right] .....	86
	Communication statistics.....	88
	Connector Pins.....	89
	Wiring Harness Diagrams.....	94