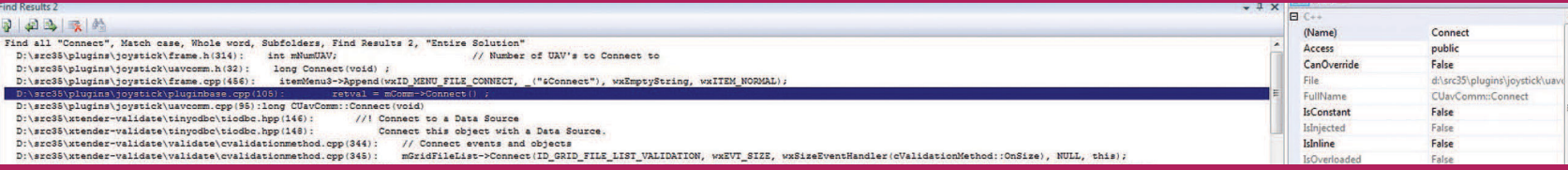


MicroPilot®

World Leader in Professional UAS Autopilots



XTENDER^{mp}

Software Developer's Kit

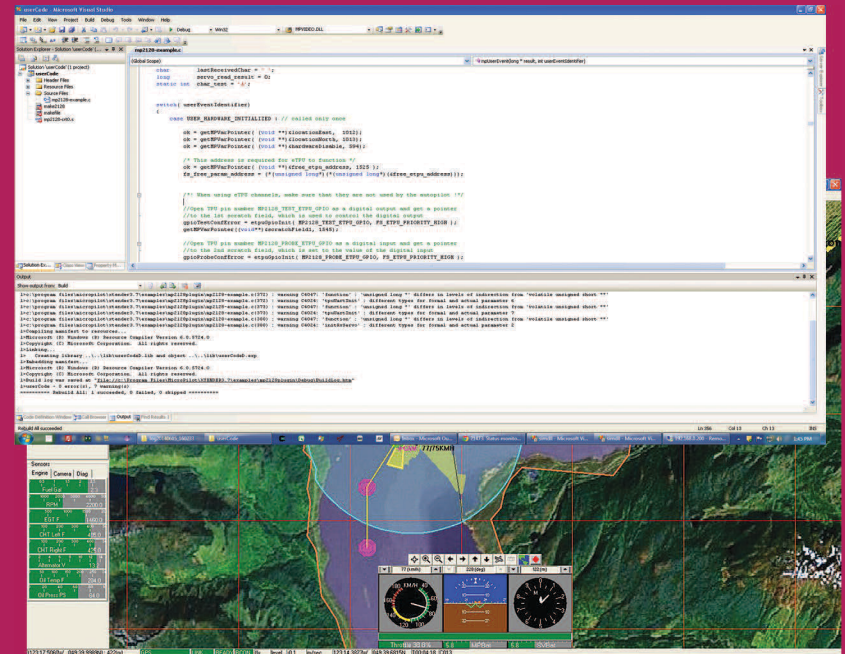
The XTENDER^{mp} software developer's kit takes the MicroPilot brand of autopilots to a whole new level. This powerful SDK is the key to differentiating your product from the competition. The XTENDER^{mp} taps into the power of a world recognized autopilot and expands it to fill the gap between standard autopilot functionality and your specific requirements.

Features Rich

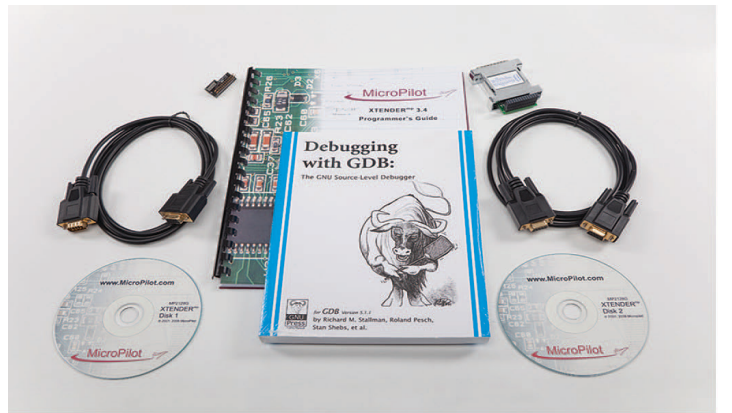
- Ability to customize control laws for enhanced control of your airframe
- Allows you to use custom software that communicates to the autopilot through HORIZON^{mp}
- Ability to develop a custom GCS
- Extends the HORIZON^{mp} to accept third party software that can access autopilot data (e.g. vision software)
- Extends the autopilot to control custom payloads and collect data from custom sensors
- Autopilot 6-DOF simulator allows you to test your code on the bench to dramatically reduce risk and increase productivity
- Allows for complete access to the autopilot state for enhanced control



MicroPilot
The choice of over 1000 clients in 85 countries



Take your UAV to the next level with this power solution



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SPECIFICATIONS

API

The XTENDER^{MP} SDK provides a flexible set of functions that allow the developer to easily design software that interacts with the autopilot.

- Integrated autopilot simulator speeds development of customer's software and provides a training mode to simplify software roll out.
- Identical API's used to connect the simulated autopilot and the real autopilot
- Thread safe, multi-threaded re-entrant API's
- API's provide access to all autopilot state information
- Windows and Linux versions available
- Compatible with any development language that supports Windows DLL (eg. Visual Basic, VB, Borland Builder)
- API functions include:
 - Transmit commands to autopilot
 - Transmit configuration settings to autopilot
 - Set individual configuration parameter
 - Retrieve multiple state fields
 - Move waypoints in-flight
 - Start/stop holding patterns
 - Start/stop threads
 - Reprogram commands in-flight
 - Initiate simulated failures
 - Capture user telemetry
 - Retrieve standard and user defined telemetry
 - Change flight mode UAV, RPV

COMMUNICATIONS

The XTENDER^{MP} SDK implements a flexible and functional communications topology.

- Allows full control of a MicroPilot autopilot connected either directly to the PC's serial port or via radio modem
- Integrated TCP/IP server extends autopilot APIs across any low latency TCP/IP network allowing applications to communicate with remotely connected MicroPilot autopilots
- Access to locally connected and remotely connected autopilots is fully transparent to the application
- Multiple processes can communicate with a single MicroPilot autopilot
- A single process can communicate with multiple MicroPilot autopilots
- Customer applications and Horizon can communicate with a MicroPilot autopilot simultaneously over the same com link

VIDEO

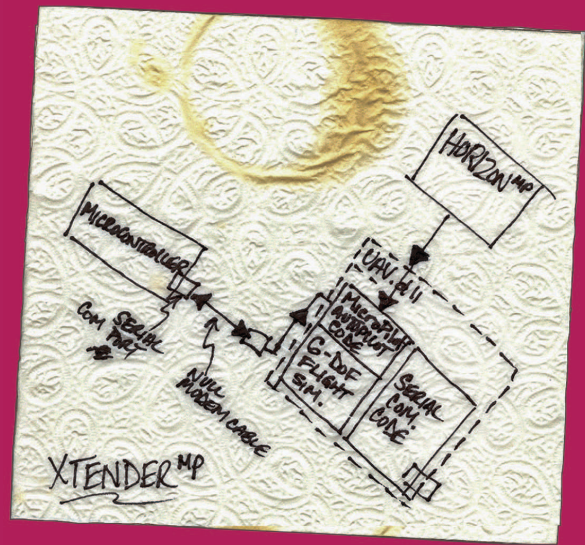
The XTENDER^{MP} SDK also includes a video API.

- Support any Windows media video source device, USB, PCI, Firewire (IEEE 1394), PCMCIA
- Frame and resolution automatically set from capture device rate
- Still and video snapshots
- Video snapshots consume only minimal CPU resources
- Video is recorded in MPEG4 Windows media format
- Snapshots include automatically generated world file
- Display video from multiple UAVs simultaneously
- Telemetry logs indexed by time and video frame number

TOOLS

The XTENDER^{MP} SDK includes the following developer's tools:

- GNU source level debugger
- Parallel port BDM probe
- GNU C compiler
- CYGWIN tool set



MicroPilot Plug-ins

MP plug-ins are code modules executed at the same time as the autopilot code and allow customers to add functionality to the autopilot to differentiate their products and close the gap between the standard autopilot functionality and their custom requirements.

- MP plug-ins can access 64K RAM for data and 64K flash for code
- MP plug-ins run under the autopilot simulator to simplify testing and speed development
- MP plug-ins can access all autopilot state fields
- MP plug-ins can provide customer specific servo mixing
- Customer defined control laws can replace any or all existing MP2028^g control laws
- MP plug-ins can access unused autopilot hardware for custom payload control and data collection
- Up to 9 I/O channels are available for MicroPilot plug-ins. Each I/O channel can be configured as one of: serial input, serial output, PWM in, PWM out, single bit input or single bit output

SIMULATOR

The XTENDER^{MP} includes a "software in the loop" 6-DOF simulator linked to autopilot code.

- Simulator update rate 200Hz
- Accepts autopilot commands via PC serial port, speeds development of embedded payload/mission controllers
- Simulates communication, engine failure, loss of GPS lock, loss of RC signal, loss of communications and low battery failures
- Availability of simulator gives end-product training mode

REQUIREMENTS

The system requirements for the XTENDER^{MP} are:

- Windows XP, Windows Vista, Windows 7 & Windows 8
- 1GB free disk space
- 256MB RAM or 512MB RAM if video is enabled
- 500MHz Pentium II or 1GHz Pentium III if video enabled
- Hardware parallel port for BDM probe
- Low latency network
- One of the following MicroPilot autopilots: MP2028^{g2}, MP2128^{g2}, MP2128^{HEL12}, MP2128^{LRC}

